

# Geodesy and Satellite Navigation

## A Lighthearted Look at a Strange Relationship

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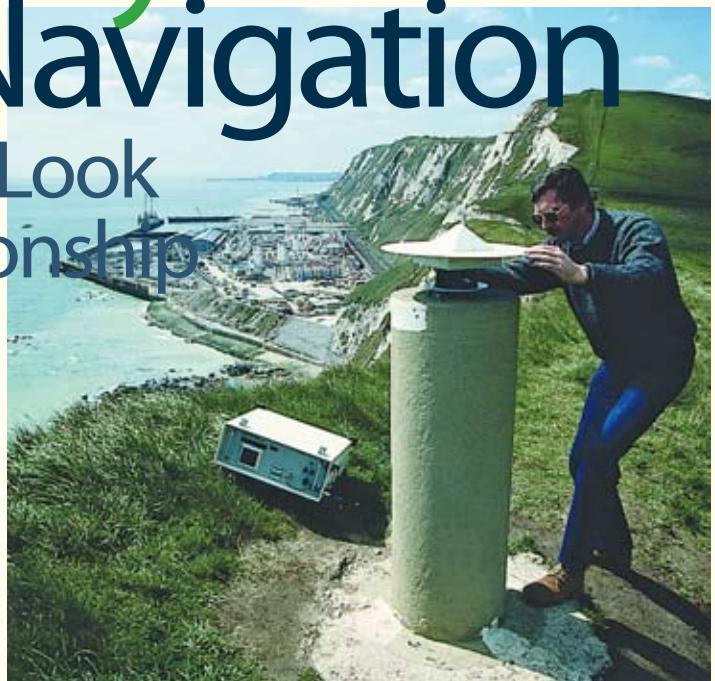


Photo courtesy of Ordnance Survey

Unbeknownst to most beneficiaries of GNSS today, satellite navigation technology owes an enormous debt to geodesy—and vice versa. A scientist and researcher who has worked both sides of the divide reflects on the mutual benefits of this sometimes irascible relationship.

Photo(above)shows a British Ordnance Survey technician setting up an early GPS geodetic receiver in the 1980s at the British end of the Franco-British Channel Tunnel (in background). The pillar that holds the GPS antenna was part of the geodetic triangulation network created in order to link the two sides of the English Channel (or La Manche in French). Electronic distance measurement devices used inside the tunnels were referenced to the GPS-based network, thus ensuring that the two halves of the tunnel did indeed meet somewhere in the middle.

There has always been a love-hate relationship between geodesy and satellite navigation. Indeed, satellite positioning started life as an extension of terrestrial geodesy. When the first satellite, Sputnik 1, started orbiting the Earth in 1957, geodesists in several countries realised that satellites offered substantial potential as a geodetic positioning and navigation tool.

The basic technologies of terrestrial geodesy of the day, notably triangulation, traversing, and precise levelling, were slow and cumbersome, mainly because of the effect of the curvature of the surface of the Earth, which limited the range of measurements to theodolite observations between points situated on hilltops, observation towers, and triangulation masts. The advent of EDM (electronic distance measurement) in the 1960s helped terrestrial geodesy, but it, too, was affected by the same limitation, namely the shortness of observable EDM ranges due to the Earth's curvature.

Earth orbiting satellites did not suffer from this drawback. They could be viewed simultaneously from several points on Earth, and therefore direction and range measurements made, provided that the space vehicles were not obscured by high natural features or tall man-made structures. This led to several new satellite geodesy positioning methodologies. The first of these was satellite triangulation, which was used initially to supplement and strengthen terrestrial triangulation networks. Satellite triangulation consisted of geodetic direction measurements derived from high power photographs



of satellite orbits made against a stellar background of stars, with known right ascension and declination. (See [Figure 1](#).)

A few years later, this was followed by range measurements to satellites, made from Earth-bound EDM equipment to corner cube reflectors placed on the early satellites. The methodology used thus far was an extension of geodetic astronomy, with little reference to physical geodesy.

This situation changed significantly when geodesists realized that they could use the Doppler shift on the signal broadcast from a satellite to obtain differential range measurements that, together with the known Keplerian orbit of the satellite, could lead to a relatively fast positioning, or navigation, method. The Keplerian orbital motion of satellites is primarily based on the Earth's gravity field, a subject of expertise by practitioners of physical geodesy.

This technical advance gave birth to Transit-Doppler, the first satellite navigation technology. Transit-Doppler was used in the late 1970s and early 1980s not only for the positioning of naval ships and of submarines surfacing in the polar regions, but also for the strengthening and scaling of national and continental terrestrial triangulation networks. [Figure 2](#) shows an early advertisement for one commercial Transit system, the CMA-772B NNS. However, practitioners soon realized that positioning by Transit-Doppler to a reasonable degree of accuracy took several minutes, and, therefore, precluding its use as a full navigation methodology, which requires quasi-instantaneous positioning.

## Enter GPS

These were the early days of a new global satellite positioning, navigation, and timing system, first called the NAVSTAR Global Positioning System, a name later shortened to just GPS. The rest is history. The early decision to base GPS on a constellation of 24 medium-Earth orbit satellites was taken on the advice, as you would expect, of geodesists at the U.S. Naval Surface Weapons Center in Dahlgren, Virginia.

The close relationship between the early GPS and geodesy was further demonstrated by the adoption of WGS84, the World Geodetic System 1984, as the basis of the 3-D coordinate system of GPS. As GPS was born during the Cold War, it was declared a

US military navigation system, with full access to NATO but only restricted access and down-graded positioning accuracies for civilian users.

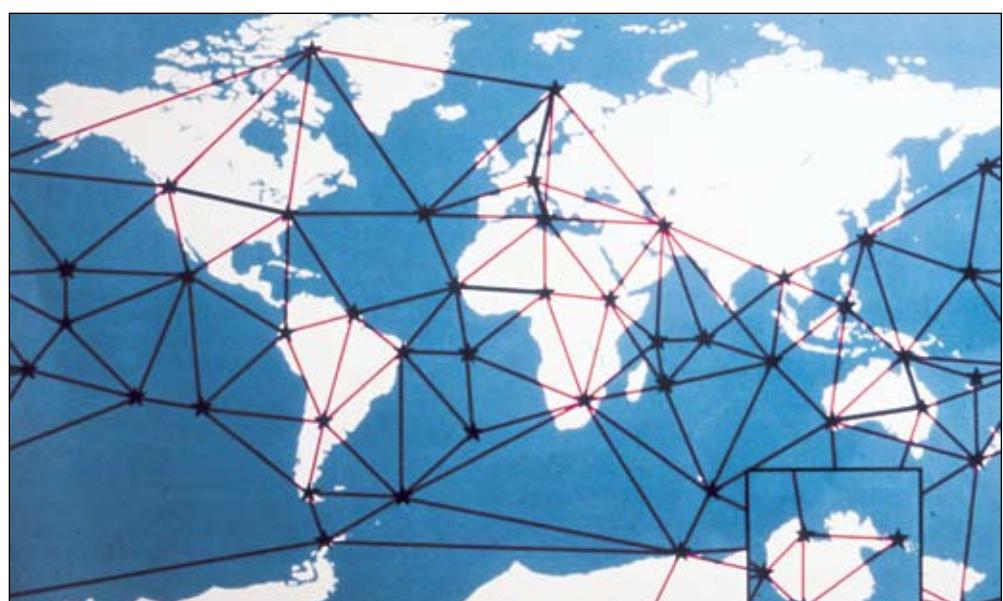
This so-called Selective Availability (SA) gave the green light to the civilian geodetic community to come up with new methodologies that could counter the effects of SA. As always, human ingenuity did not disappoint, and two new

differential techniques were developed. The first was the differential GPS (DGPS) technique, which improved relative positioning accuracies of GPS by at one order of magnitude, down to a few meters.

As a result, DGPS soon became the standard methodology for the offshore positioning of oil platforms, pipelines, etc.

The next advance in improving the accuracy of satellite positioning was made on the advice of radio-astronomers, who proposed replacing the standard GPS pseudorange measurements, which are based on timing the modulated signal from satellite to receiver. Instead, they suggested making measurements on the basic carrier frequencies of these signals, just as they did with extra-galactic signals arriving at, say, two widely spaced radio telescopes in so-called very long baseline interferometry (VLBI), leading as a by-product to the Cartesian coordinate differences between the two telescopes. This was the beginning of centimetric positioning by the carrier phase GPS method, which was later developed further by geodesists into kinematic GPS and centimetric navigation.

GPS had now become the universal high precision quasi-instantaneous positioning and navigation tool, creating the basis for hundreds of new applications. Again, geodesists led the way, concentrating on high precision scientific and





**FIGURE 2** An advertisement for a commercial Transit system, the CMA-772B NNS.

engineering applications. These included surveying and mapping, positioning in offshore engineering, the monitoring of local crustal dynamics and plate tectonics, the relative vertical movements of tide gauges, and the continuous 3-D movements of critical engineering structures, such as tall buildings, dams, reservoirs, and long suspension bridges. All of these applications required very high relative positioning accuracies, but not quasi-instantaneously as in the safety-critical navigation and landing of civilian aircraft. This came much later.

## Geodesy and Navigation

Initially, GPS was considered as a standard navigation tool for military vehicles on land, sea, and air, but not for safety-critical civilian transportation. This was because, unlike military positioning and navigation, safety-critical civilian transportation not only requires quasi-instantaneous and accurate positioning, but also so-called “high integrity and good coverage.”

Geodesists will immediately realize that “integrity” stands for the geodetic concept of “reliability,” whereas “coverage” refers to the availability of a sufficient number of satellites that can be sighted by a receiver continuously and are not obscured by natural or man-made obstructions, such as high mountains, tall buildings, and the wings of an aircraft. On its own, GPS cannot meet these requirements to the level required in safety-critical civilian transportation. Military transportation, on the other hand, has relatively modest requirements, which can be met by GPS. Indeed, you do not become a NATO Air Force pilot if you want a safe life. Flying as a passenger in a commercial airline is something else all together.

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The penetration of satellite navigation, and primarily GPS, into civil aviation involved yet again, as you would expect, geodesists. They had to develop jointly with the civil aviation community the necessary theoretical and practical tools, which could be used to establish and quantify their requirements of accuracy, integrity, and coverage. This involved the use of existing geodetic tools, such as the *covariance matrix*, the analysis of *least squares residuals*, and the well-established geodetic *reliability* measures. New tools were also introduced, such as the concept of RAIM or *receiver autonomous integrity monitoring*, based on the analysis of the least squares residuals.

## Persuading Non-Geodesists

These geodetic tools, which were highly beneficial to the civil aviation community, initiated a fruitful, long-term collaboration between the two communities. However, this has not always been a straightforward and smooth relationship, and it involved — especially at the beginning — a deep suspicion of these “academic” geo-scientists. Here are a few notable examples of this love-hate relationship.

As a general rule, the existing civil aviation horizontal coordinates were based on latitudes and longitudes, with no particular reference to a *reference datum*. Heights in civil aviation were and still are based on barometric altimetry, on the assumption that all that matters is “the relative heighting between airplanes,” which is not affected significantly by a change in barometric pressure.

This assumption disregards, of course, the fact that the heights of natural features on the ground, such as mountains, do not change with changing barometric pressure. The first challenge was to convince the international civil aviation community that their horizontal coordinates, that is, latitudes and longitudes, required a proper geodetic datum and, as GPS was being contemplated as a future navigation tool, it made sense to adopt the same reference datum, namely WGS84. It took a while to convince the community to accept that.

The adoption of WGS84 led to the resurveying of most airports, runways, and various en route and landing navigation aids in order to bring them into WGS84, in preparation

for the introduction of GPS. This led to the discovery of some large discrepancies, at airports and among navaids in many countries, between the existing horizontal coordinate values and their new WGS84 equivalents. Geodesists will be familiar with such occurrences, whenever they start dealing with a new community, whether they are civil or offshore engineers, oceanographers or meteorologists.

The first GPS receivers did not lend themselves to mass market adoption (See **Figure 3.**) Geodesists of a certain age will also remember some of the earliest commercial GPS receivers, such as the TI 4100 receivers, made by Texas



Instruments. (See accompanying photo.) These early receivers operated by measuring sequentially four pseudoranges to four different satellites. Consequently, the receivers were programmed to first check the geometry of the satellites in view and decide on the best four in terms of geometrical configuration.

However, later on, with the emergence of new receivers that could measure all the available pseudoranges quasi-simultaneously, there was no need to carry on with measurements only to the “best four” satellites. One could track all available satellite signals and process these measurements by least squares, rejecting those with relatively large residuals, if any. This standard processing of observations is bread-and-butter stuff to surveyors and geodesists. However, this was not the case with a number of navigation experts, who persisted on recommending the use of only the “best four” satellites for quite sometime, before they finally abandoned the practice.

## A New Era of GNSS

Satellite navigation and positioning has changed substantially and significantly over the last 5 to 10 years. With Galileo in its development and in-orbit validation phase, the future developments in GPS IIF and GPS III, renewed interest in GLONASS, and satellite navigation initiatives in Japan, China, India, Australia, and several other countries, GNSS or the Global Navigation Satellite System is moving from being a concept, largely based on GPS alone, to a full global reality. A comprehensive program of GPS modernization currently under way aims to deliver significant improvements to both military and civil users.

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The earliest mass-market applications of GPS involved road vehicles and mobile phones. In both cases, the twin aims are navigation (*where am I, and how do I go to my destination?*) and tracking (*where is he, she, or it?*). In the case of road vehicle tracking, successful applications include fleet monitoring (taxis or road transport companies), theft recovery of private cars, “black box” incident recorders, and the transport of hazardous or valuable cargoes. Typically, most of these applications share three common features, namely prior knowledge of the proposed route, the continuous tracking of position and velocity by GPS, and the trigger of an alarm by a significant deviation.

Similarly, a number of GPS tracking applications use mobile phone technology (GSM or GPRS), but these are not

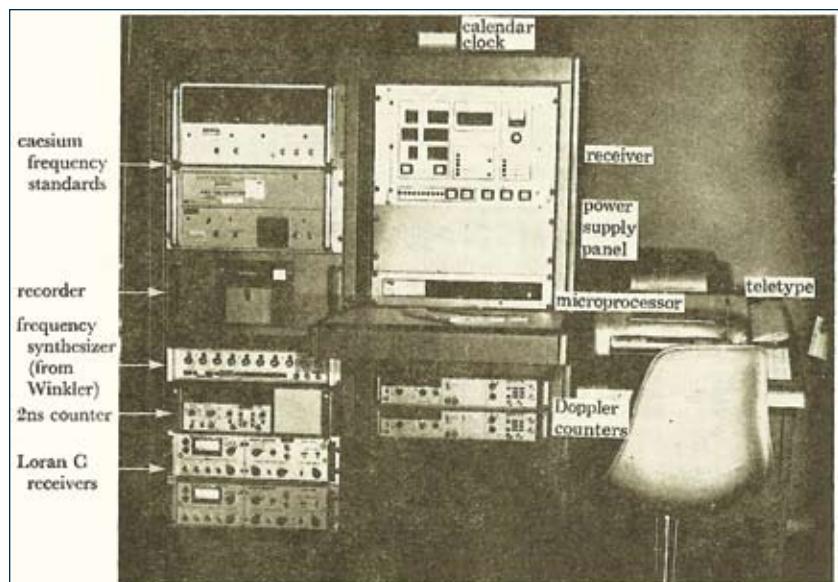


FIGURE 3 The first GPS receivers did not lend themselves to mass market adoption.

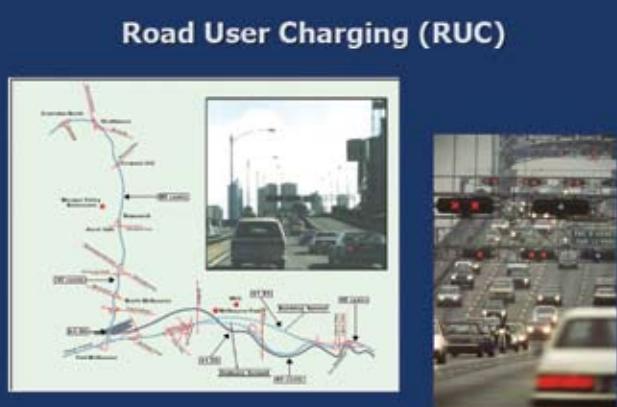


EARLY MODEL Texas Instruments' TI 4100 receiver.

as developed and widespread as vehicle tracking. Typically, these involve vulnerable people, such as young children, the elderly, key workers in some risky environments (for instance, railways), individuals with a chronic or contagious disease, and even VIPs. Person tracking with GPS+telematics could also involve judicial cases (ordered by a court of law), of suspected criminals or anti-social elements. Other proposed applications include environmental information, location-based security, and location-sensitive marketing.

On its own, a GPS-enabled phone offers location and communication. This may answer the questions “Where is she or he?” and “Where am I?” but nothing more. However, when position and communication are combined with an appropriate geographic information system (GIS) database and a direction sensor, the combined system could answer two other very important questions, namely “What's around me?” and “What's that building over there?”

This could be achieved by a GPS+compass device, providing positional and directional data, which the mobile phone



**FIGURE 4** Road user charging is one of the emerging applications for GNSS.

or the PDA transmits to a remote server. The server calculates the user's position and identifies the building along the measured azimuth, gets the relevant information from the database, and sends it back to the client. This is clearly valuable for the public utilities (water, gas, electricity, TV), shopping and leisure (restaurant menus, theater tickets), house hunting (details of the property advertised for sale), and of course, for visitors and tourists (museums, notable buildings, archaeological sites).

Leaving mobile phones aside, satellite navigation can also be used for location-based-security. For example, a briefcase or a portable PC can be programmed to unlock safely only in a specified location and nowhere else. This would minimize the risk of sensitive military or commercial material falling into the wrong hands. Some working prototype systems already exist. Other location-and-context-based applications under consideration include the marketing and selling of goods, the reception of pay-TV, credit card security, spectator sports, road user charging (see Figure 4) and many others.

Indeed, the qualification of "critical application" is no longer restricted to *safety-critical transportation*, but it also applies now to *financial-critical*, *legal-critical*, *security-critical*, and *business-critical* applications as well. This creates a problem with standard off-the-shelf autonomous GPS receivers, which cannot operate indoors, because of signal attenuation and multipath. Over the last few years, GPS chip and receiver manufacturers have tried, with some success, to develop high sensitivity GPS (or HS-GPS). The latest HS-GPS receivers, which incorporate up to 200,000 correlators operating in parallel, make it relatively easy to identify true pseudoranges from among the many signal and multipath reflections. Several manufacturers in the United States, Japan, Korea, and Europe, already advertise HS-GPS chips, and many other companies use such chipsets in their receivers.

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## GNSS Evolution

Like nearly all the technologies that preceded it, satellite navigation and positioning is going through the standard stages of development from birth to maturity. Older surveyors and geodesists may well remember the advent of EDM, using microwaves or lightwaves in the late 1960s and the 1970s. When the first EDM instruments were introduced, the distances measured were also measured with tapes, just in case. Then came the second phase, when surveyors became fully confident about EDM and used it routinely for fast and precise range measurements. It took a few years and several critical mistakes in local mapping and national triangulation, to realize that EDM instruments could go wrong and that they had to be calibrated regularly in order to determine their accuracy and systematic biases.

The development of satellite navigation and positioning is following practically the same stages as EDM did 40 years ago. Only now we can formalize these successive stages of development of a technology and give them names by using Gartner's famous "Hype Cycle Curve," which was invented about 10 years ago in conjunction with new information technology products. Using a simplified version, these successive stages of technology development are now formally called "Technology Trigger," followed by "Peak of Inflated Expectation," leading to "Trough of Disillusionment," happily followed by the "Slope of Enlightenment," and hopefully leading to the "Plateau of Productivity."

As I write this, the first Galileo satellite, GIOVE-A, has been launched and tested successfully, opening a new era in satellite navigation. Hopefully, this will lead to the development of a large number of new critical appli-

cations — and involve close collaboration with geodesy and several other related disciplines — for the benefit of business, government and society.

Here is one last example about the strange relationship between geodesy and GPS. The U.S. delegation to the International Telecommunications Union (ITU) recently proposed to abolish leap seconds, and thus cut the link between Solar Time and Coordinated Universal Time (UTC) and *ipso facto* GPS Time. At present, whenever the difference between UTC and Solar Time approaches 0.7 second, a leap second correction is made in order to keep the difference between them under 0.9 second. This is done every few years on the recommendation of the International Earth Rotation and Reference Systems Service, which monitors continuously the difference between Solar Time and UTC.

This leap second correction, which has to be applied every few years to GPS Time, apparently causes software problems because it has to be programmed manually. However, con-

sidering the difficulties that this change would cause to other scientific communities, such as astronomers, and even to users of GPS time itself for some critical applications, the U.S. proposal has now been postponed for the time being.

In conclusion, I must declare a conflict of interest.

Although all the work I do at present involves GNSS, my academic background is clearly in geodesy. However, a change is in the air now, as safety-critical transportation is no longer the only critical application that has to be catered to. It has now been joined by several other emerging critical applications, notably financial-critical, legal-critical, security-critical and business-critical applications, which will also require nearly the same level of accuracy, integrity and coverage as safety-critical transportation. This is where geodesy could step in again and create some new statistical tools, which will differentiate between the navigation and positioning systems on offer, and assess their suitability for the specific critical application.

## Author

Vidal Ashkenazi is CEO of U.K.-based Nottingham Scientific Ltd, and a Fellow of the Royal Academy of Engineering. He was the founding director of one of the leading space geodesy research institutes in Europe and has supervised about 50 doctoral (Ph.D.) students, many of whom now occupy senior positions in universities and industry in several countries. Ashkenazi has acted as a consultant to a large number of government and commercial organizations around the world. He has published several hundred papers and has been invited to give keynote lectures in many international conferences and symposia. Ashkenazi received a medal by the president of the Royal Society in recognition of his "significant contribution to the exploitation of GPS in a wider range of scientific and commercial applications." Ashkenazi achieved doctorates in philosophy and physical science from Oxford University in the United Kingdom. He received a bachelor of science in civil engineering and master of science in geodesy from Technion/Israel Institute of Technology. 



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